

### MERIT Hg System Final Design Review

# **Hg Target System Controls**

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## Outline

- Operating environment
- Requirements / constraints
- Power requirements
- Instrumentation
- Control system scheme
- Issues

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# **CERN Tunnel Plan View**



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# **MERIT Layout**



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#### **Control System Requirements & Constraints**

- No existing power available in tunnel
- Control system mounted on hydraulic pump reservoir
- Operator controls 60m away
- Will require some level of communication with other control systems (solenoid, beam, diagnostics) and/or a supervisory control system





# **Operating Scenario**

	Solenoio	d **			
Time	Cryogenics	Power	<b>Target Pump</b>	<b>Proton Beam</b>	Optical
(sec.)		Supply	System		Diagnostic
minus 30	Magnet full of	Standby	Fill Hg supply	Call for beam	Off
	LN <sub>2</sub> @ 80°K		line		
minus 10	Purge LN <sub>2</sub> with	Standby	Standby	Wait for beam	Standby
1000	gaseous He				
0 to 9.5	Magnet full of	Start ramp	Ramp Hg to full	Wait for beam	Standby
	He gas	to full	flow		
		current			
8 to 9.0	Magnet full of	Ramping to	Steady state Hg	Wait for beam	Turn on laser
	He gas	full current	jet		lighting
9.5 to	Magnet full of	At full	Steady state Hg	24 GeV, 1 MW	Operate high
10.5	He gas	current	jet		speed camera
10.5 to	Magnet full of	Begin de-	Shut down	Standby	Turn off laser
11.0	He gas	energizing	syringe pump		light and
					camera
11.0 to	Magnet full of	De-energize	Standby	Standby	Off
15.0	He gas	to zero			
15.0 to	Fill magnet with	Cool down	Refill syringe	Standby	Off
1800.0*	LN <sub>2</sub> @ 80°K	to ~80°K	cylinder		

\* Assumes a 30-minute dwell period.
\*\* Solenoid power supply is in "Standby" for zero-field operation.

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#### **Power Requirements**

- Hydraulic pump 380/460VAC, 50-60Hz, 60A
- Proportional control valve 24VDC
- Heater foil 120VAC
- Hg vapor monitor 120VAC
- Instruments 24VDC



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# **Minimum Signal Requirements**

- Trigger (time till pulse)
- Ready signal from Hg system
- Enable signal from supervisory control system
   Also used as abort signal



# **Instrumentation & Sensors**

Controlled Components							
Hydraulic pump	Proportional control valve*	Heater foil					
Analog Sensor Inputs							
Hg discharge pressure	Hg level	Hg sump thermocouple	Secondary containment thermocouple				
Cylinder 1 position*	Cylinder 2 position	Hg vapor 1	Hg vapor 2				
Hydraulic fluid high pressure	Hydraulic fluid low pressure	Beam window 1 pressure*	Beam window 2 pressure*				
Digital Sensor Inputs							
Hydraulic filter dirty switch	Hydraulic low level switch	Conductivity probe					

\* Critical for system operation or safety

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#### **Proportional Directional Control** Valve

#### Bosch Rexroth 4WREE

- Operating pressure: up to 3000psi (210 bar)
- Nominal flow: 8.45gpm (32 l/min)
- Sensitivity: <= 0.05% (equates to 0.003 m/sec nozzle velocity)
- Supply voltage: +24VDC
- Command signal: ±10VDC







# **Original Position Sensor**

- Temposonics G-series linear position sensor
  - Measured variable: displacement
  - Measuring range: 2-100in
  - Repeatability: 0.001% full stroke
  - Output: voltage or current
  - Update time: <1ms</p>
  - Supply voltage: +24VDC
- Installed in hydraulic cylinder
- Problems: on-board electronics, operates using magnetic field





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#### **Current Position Sensor**



#### Celesco CLWG linear potentiometer

- Redundant sensor on cylinder #2
- Aluminum body
- Voltage divider output
  - Variable resistor, no on-board electronics
  - Repeatability < 0.01mm</li>
  - Linearity 0.05%FS for 450mm range (0.225mm)
- Position sensor critical to system control
  - Piston start/stop locations
  - Piston position/velocity ⇒ Hg flow rate ⇒ Jet velocity
  - Electrical noise may be problem

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# LabView-Based Control System

- Remote control over long distance limited choices
  - Analog I/O modules need to be close to equipment and power supplies
- LabView controller on laptop computer was chosen
  - National Instruments recommends CompactPCI I/O modules
  - Communicates to laptop via EtherNet cable
  - Allows custom operator interface, data logging if required during development
  - Should allow straightforward integration with other control systems
- Control system development to begin late October

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#### Procurement

 National Instruments hardware & software procured by Princeton

LabView software already procured

- Laptop computer provided by BNL
- Most instruments specified in Hg delivery system procurement package



#### Conclusions

- Control system scheme chosen
- System development to begin November 2005
   Ready when syringe delivered
- Most instruments provided with Hg delivery system
- Integration with supervisory control system TBD

