Cylinder Rolling inside a Fixed Cylinder

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1 Problem

Discuss the motion of a cylinder that rolls without slipping inside a fixed cylinder whose axis is horizontal.

2 Solution

This problem is a simpler version of the case of one cylinder rolling inside another rolling cylinder [1].

A cylinder (or sphere) of mass m, radius r, and moment of inertia kmr^2 about its center¹ is in contact with a cylindrical surface of radius R > r as sketched below.



The center of the cylinder of radius r makes angle θ with respect to a vertical through the center(line) of the cylinder of radius R.

The condition of rolling without slipping for the inner cylinder is that when its center has rolled from $\theta = 0$ to θ , the initial point of contact of the two cylinders makes angle ϕ with respect to the present point of contact, which is at distance $r\theta$ from the initial point of contact along the surface of the outer cylinder. That is,

$$r\phi = R\theta. \tag{1}$$

The angular velocity ω of the inner, rolling cylinder is not $\dot{\phi}$, but is to be measured with respect to a fixed direction in the lab frame, such as the vertical. That is,

$$\omega = \dot{\phi} - \dot{\theta} = \dot{\theta} \frac{R - r}{r} \,. \tag{2}$$

The angular acceleration α of the inner cylinder is then,

$$\alpha = \dot{\omega} = \ddot{\theta} \frac{R-r}{r} \,. \tag{3}$$

 $^{^{1}}k = 1$ for a cylindrical shell, k = 1/2 for a uniform cylinder, and k = 2/5 for a uniform sphere, etc.

The potential energy of the inner cylinder, taken to be zero when $\theta = 0$, is,

$$PE = mg(R - r)(1 - \cos\theta).$$
(4)

The kinetic energy of the inner cylinder is, whose center-of-mass velocity is $v = (R - r)\dot{\theta}$

$$KE = \frac{mv^2}{2} + \frac{I\omega^2}{2} = \frac{mr^2\dot{\theta}^2}{2} + \frac{kmr^2\dot{\theta}^2}{2}\left(\frac{R-r}{r}\right)^2 = \frac{m\dot{\theta}^2}{2}[r^2 + k(R-r)^2].$$
 (5)

Assuming no slipping of the inner cylinder, the conserved energy E of the system, with initial velocity v_0 when $\theta = 0$, is,

$$E = KE + PE = \frac{mv_0^2}{2} = \frac{m\dot{\theta}^2}{2}(1+k)(R-r)^2 + mg(R-r)(1-\cos\theta)$$
$$= \frac{mv^2}{2}(1+k) + mg(R-r)(1-\cos\theta).$$
(6)

$$v^{2} = \frac{m}{1+k} [v_{0}^{2} - 2g(R-r)(1-\cos\theta)].$$
(7)

The equation of motion in angle θ follows from the time derivative of eq. (6),

$$\ddot{\theta} = -\frac{g\sin\theta}{(1+k)(R-r)}\,.\tag{8}$$

Note that $\ddot{\theta}$ is negative for positive θ , and hence the angular acceleration α of eq. (3) is also negative for positive θ ; *i.e.*, counterclockwise in the figure on p. 1. Hence, the force F of friction at the contact point is directed up the slope of the outer cylinder.

2.1 Small Oscillation about $\theta = 0$

For small θ , the equation of motion (8) has the form,

$$\ddot{\theta} \approx -\frac{g}{(1+k)(R-r)}\theta,\tag{9}$$

which has the form of simple-harmonic oscillation, $\theta = \theta_0 \sin \Omega t \ (\Rightarrow v_0 = (R - r) \Omega \theta_0)$, with angular frequency Ω given by,

$$\Omega = \sqrt{\frac{g}{(1+k)(R-r)}}.$$
(10)

2.2 At What Angle Does the Inner Cylinder Slip?

If v_0 is large enough that angle θ reaches 90°, then the inner cylinder slips/falls at that angle. The condition for this follows from eq. (6) as,

$$v_0^2(\theta \ge 90^\circ) \ge 2g(R-r).$$
 (11)

When $\theta_{\text{max}} < 90^{\circ}$, the inner cylinder will slip if the friction force F between the inner and outer cylinders exceeds μN , where μ is the coefficient of static friction between the inner and outer cylinder.

The normal (radial) force is related to the centripetal acceleration $mv^2/(R-r)$ of the inner cylinder by, recalling eq. (7),

$$N - mg\sin\theta = \frac{mv^2}{R - r}, \quad N = mg\sin\theta + \frac{m}{1 + k}\frac{v_0^2 - 2g(R - r)(1 - \cos\theta)}{R - r}.$$
 (12)

The friction force F must be large enough to satisfy the torque equation about the center of mass of the inner cylinder,

$$\tau_{\rm cm} = rF = -I\alpha = -kmr^2 \ddot{\theta} \frac{R-r}{r} = kmr(R-r) \frac{g\sin\theta}{(1+k)(R-r)} \frac{R-r}{r} = \frac{kmg(R-r)\sin\theta}{1+k},$$
(13)
$$F = \frac{kmg(R-r)\sin\theta}{(1+k)r},$$
(14)

recalling eqs. (3) and (9). The slip angle θ_{slip} , if it exists, is given by the condition, $F = \mu N$,

$$\frac{k(R-r)g\sin\theta_{\rm slip}}{(1+k)r}$$
$$= \mu \left[g\sin\theta_{\rm slip} + \frac{v_0^2 - 2g(R-r)(1-\cos\theta_{\rm slip})}{(1+k)(R-r)}\right].$$
(15)

For the inner cylinder to reach angle $\theta \leq 90^{\circ}$ without slipping, the coefficient of friction must satisfy,

$$\mu(\theta) > \frac{k(R-r)g\sin\theta_{\rm slip}}{(1+k)r} / \left[g\sin\theta_{\rm slip} + \frac{v_0^2 - 2g(R-r)(1-\cos\theta_{\rm slip})}{(1+k)(R-r)}\right] = \frac{k}{1+k}\frac{R-r}{r}.$$
 (16)

using $\theta_{\rm slip} = 90^{\circ}$ and $v_0^2 = 2g(R-r)$ as the minimum to reach $\theta = 90^{\circ}$.

For larger ratio R/r, the coefficient of static friction μ must be larger for the inner cylinder to reach $\theta = 90^{\circ}$, *i.e.*, the height of the center of the outer cylinder.

References

 K.T. McDonald, Cylinder Rolling inside Another Rolling Cylinder, (Oct. 23, 2014), http://kirkmcd.princeton.edu/examples/2cylinders_in.pdf